

Project

Goals

CaaS aims to provide programmers and data scientists a simple and general solution to language interoperability:

Our approach is to generalize a high-energy physics analysis code ("Cling") to a generally accessible and fully functional tool that is part of LLVM/Clang.

- developers including

Project Results and Applications



Project Accomplishments

• Advance interpretative technology to provide scientists a state-of-the-art C++ execution environment • Enable functionality to provide dynamic, native-like, runtime interoperability between C++ and Python • Allow seamless utilization of heterogeneous hardware (e.g., hardware accelerators) • To enable rapid application development even with a complex codebase

 LLVM community engagement / acceptance of CaaS concept and approach • Initial release of Clang-Repl achieved in LLVM13

• Clang-Repl based plugin (Clad) implemented and demonstrated including offload of calculations to GPU LibInterop design completed after extensive community discussion. Now co-developing with application

• CPPYY package enabling run-time python <-> C++ bindings

• Xeus based Jupyter plugin supporting interoperability and data exchange between C++ and python Science applications include automatic differentiation, uncertainty quantification, and embedded device control

out-of-line)	1.5
	16
	27
	68
	68
	104
a pure overhead measure (zero of global interpreter lock (GIL) nality for speed to "static" over runtime binding	o work) release s (*) lower is bett
- 26 -	
	Clang-Repl enab
libIncremental Clang-Repl libInterOp C++ as a service	Xeus-Repl C++ in notebooks
	s a pure overhead measure (zero : of global interpreter lock (GIL) nality for speed to "static" over runtime binding -26- -26-

and applications. Visit us at <u>https://compiler-research.org</u>

CSSI Element: C++ as a service - rapid software development and dynamic interoperability with Python and beyond Princeton University: David Lange (PI), Ioana Ifrim, and Vassil Vassilev. Open-source contributors, students, interns: Parth Arora, Sara Bellei, Purva Chaudhari, Anubhab Ghosh, Matheus Izvekov, Manish Kausik, Sunho Kim, Baidyanath Kundu, Tapasweni Pathak, Rohit Rathaur, Garima Singh, Roman Shakhov, Surya Somayyajula, Jun Zhang





$$\chi^2 = \sum_{i=1}^{N} \frac{\left(Y_i - f(x_i, \mathbf{p})\right)^2}{\sigma_i^2}$$

Case Study: Simpson's Rule Results				<pre>long double f(long double x) { long double pi = M_PI; long double tmp = x * pi;</pre>	
Precision configurations	Absolute Error	Clad's Estimated Upperbound	Variables in lower precision (out of 11)	<pre>long double tmp = x pr; long double tmp2 = sin(tmp) * pi; return tmp2; }</pre>	
10-byte extended precision (<i>long double</i>)	4.07e-14	3.1e-12	0	<pre>long double simpsons(double a, double b) { int n = 1000000;</pre>	
Clad's mixed precision	4.08e-14	3.0e-12	6	<pre>double h = (b - a) / (2.0 * n); long double x = a; double tmp;</pre>	
IEEE double-precision (double)	6.8e-11	6.2e-9	-	<pre>double fa = f(a), fb = f(b); long double s1 = fa;</pre>	
IEEE single-precision (<i>float</i>)	0.038	3.31	-	<pre>for(int l = 0; l < n; l++) { x = x + h; s1 = s1 + 4.0 * f(x);</pre>	
"Demoting" low-sens perform Clad's estimate also ag final error. This can	itivity variable ance by ~10% rees that the be useful in	es to lower prec 6 in this example re is no significa the cases where	cision improves e. Int change in the e an accurate	<pre>x = x + h; s1 = s1 + 2.0 * f(x); } s1 = s1 - fb; tmp = h / 3.0; s1 = s1 * tmp;</pre>	

ground-truth comparison is not available